

Mobility Management

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Mobility Models for Systems Evaluation - A Survey

By Musolesi and Mascolo

Mobility Patterns Categories

+ Trace Models

- Obtained by measurements of deployed systems
- Consists of logs of connectivity or location information
- Related to a specific scenario
- Publicly available traces are limited

+ Synthetic Models

- Mathematical models - sets of equations that try to capture the movement of the devices

+ Design Synthetic Models from Real Traces

- Capture and model key statistical properties of the traces
- Reproduce and generalize them into simulators' input data

+ Social Network Theories

- Mobile devices are carried by humans

Purely Synthetic Mobility Models

Represent movements of a single node

+ Random Walk Mobility Model

- Purely random movement
- Not suitable for wireless environment

+ Random Waypoint Mobility Model

- Addition of pauses to the Random Walk
- Not realistic

- Initial placement of nodes
- Nodes concentrate in the middle of a bounded area
- Speed decay over time

- Random Trip Mobility Model

- Generalization of Random Walk and Random Waypoint
- Sample the initial simulation state from the stationary regime to solve the problem of reaching time-stationary

Synthetic Group Mobility Model

Model behavior of groups that move together, i.e. platoon of soldiers, groups of students or colleagues.

+ Structured Group Mobility Model

- Link movements of node to the position of a subset of the other nodes of the network
- Not realistic
 - Groups move randomly
 - Memberships are hard-wired: nodes cannot join other groups during simulation

+ Heterogeneous Random Walk Model

- Reproduce the presence of clusters that are observed in real-world traces to study the emergence of clustered networks

Trace-based Mobility Model

Exploit available measurements to generate synthetic traces characterized by the same statistical properties of the real ones

+ WLAN Campus Usage Traces

- Movements between areas of campus represented by means of Markov model
- Session duration data follow power-law distribution
- Pause time and speed follow log-normal distribution

+ Movements inside downtown Osaka

- No reliance on any wireless measurements
- Empirical methodology to analyze characteristics of crowds in instants of time and maps of the city

Characterization and Analytical Models of Human Connectivity

- + Power-law distributions to represent contacts duration and inter-contacts time
- + Beyond characteristic time of 12 hours, the CCDF exhibits exponential decay

⇒ *Do not abandon Random Waypoint Model yet!*

- + User registration patterns exhibit a distinct hierarchy and WLAN APs can be clustered based on registration patterns
- + Heavy-tailed Wei-bull distribution to model cluster size distributions, intra-cluster transition probabilities, and trace lengths
- + Modeling of animal movements such as animal foraging behavior

Social Network-Based Mobility Models

- + Devices are carried by humans, so the movement of such devices is based on human decisions and social behavior
- + Presence of clusters dependent on the relationships among members of the social group
- + Fundamentally different from other types of networked systems - clustering is far greater than in networks based on the stochastic models

Social Network Based Mobility Models - Community Based Mobility Model

- + Hosts grouped together based on social relationships among individuals
- + Grouping mapped to a topographical space, with topography biased by the strength of social ties
- + Movements of hosts are driven by social relationships among them
- + Fundamental parameters, such as distribution of contacts duration and inter-contacts time, provide good approximation of real movements
- + Approximate power law holds over a large range of values for inter-contacts time
- + Contacts duration distribution follows a power law for a more limited range of values

Social Network Based Mobility Models - Community Based Mobility Model, Cont.

- + Weighted graph to present social networks $[0,1]$. 0 = no interactions between nodes/person. 1= strong social interaction.
- + Network represented by interaction matrix M : m_{ij} = interaction between individual i and j . $m_{ij} = 1$ where $i=j$.
- + Interaction matrix to generate connectivity matrix C : $c_{ij} = 1$ if $m_{ij} >$ specific threshold.
- + A host is initially positioned in a certain square in the grid. A goal is assigned to host to drive movement. Host i is associated to square S_{pq} if its goal is inside S_{pq} .
- + Each S_{pq} exerts a certain social attractivity to a certain host. The social attractivity of a square is a measure of its importance to host in terms of the social relationships.

Social Network Based Mobility Models - Community Based Mobility Model, Cont.

Social attractivity of square S_{pq} towards host $i = SA_{pq(i)}$:

$$SA_{p,q_i} = \frac{\sum_{j \in C_{S_{p,q}}} m_{i,j}}{w}$$

w = the cardinality of $C_{S_{pq}}$ (i.e. the # of hosts associated to the square S_{pq})

2 mechanisms for selection of next goal:

- + Deterministic: based on selection of square that exerts the highest attractivity. goals are chosen only inside squares associated to their community.
- + Probabilistic: based on probability of selection of a goal in a certain square proportional to their attractivities.

Social Network Based Mobility Models - Community Based Mobility Model, Cont.

- Probabilistic mechanism: hosts randomly select next goals in other squares of the simulation area, with a certain non-zero probability
- + New goals are chosen inside the same area when the input social network is composed by loosely connected communities
 - + Host may also be attracted to a different square when it has strong relationships with both communities.
 - + Probability of selecting square $S_{pq(i)}$:

$$P(s = S_{p,q_i}) = \frac{SA_{p,q_i} + d}{\sum_{j=1}^{p \times q} (SA_{p,q_j} + d)}$$

d = random value greater than 1

Connectivity Models

Focuses on the evolution of the emergent connectivity graph that is changing over time as nodes move.

+ Connectivity Trace Generator (CTG)

- Probability distributions describing the patterns of collocation of mobile users (i.e. contact duration and inter-contacts time) are direct inputs of a synthetic traces generation tool
 - Input of CTG is a set of real traces - processed by a trace analyzer to generate parameters describing user connectivity
 - Parameters are the coefficients of the curves used to approximate the distributions of:
 - Inter-contacts time
 - Contract durations
 - Link degrees characterizing the social graph of the contacts among the users.
- Connectivity graph as basis for time-varying graph of instant connectivity for each instant t

Testing Tools and Mobility Modeling

- + Most popular are NS-3, Glomosim, Opnet
 - + Discrete-event simulators: OMNeT++, Parsec
 - + Different simulators show significant differences
 - Various modeling techniques and assumptions
 - Different methodologies followed by researchers.
 - + Use of unrealistic mobility models
 - + Absence of a meaningful number of runs to achieve a sufficient statistical validity of the results
- ⇒ Lack of confidence in simulation results to evaluate the performance of protocols and systems!

Outlook

- + Identify common features of human mobility
 - Increase availability of mobility traces extracted from heterogeneous environments
- + Connectivity Models and Mobility Models are complementary, not alternative
 - Integrate the use of connectivity and mobility models to characterize human mobility
- + Benchmarks for Protocol and System Evaluation: Choice of values for parameters of simulations are extremely variable
- + Limited number of available tools for academic and industrial testing of mobile applications
- + Available traces do not follow common standard

The Random Trip Model: Stability, Stationary Regime, and Perfect Simulation

By Boudec and Vojnovic

Overview

- + Provide a class of "stable" mobility models to accommodate a large variety of examples
- + Provide an algorithm to run "perfect simulation" of these models
- + Model of random with independent node movements.
 - Independent node movements are defined by specifying a random process of movement for a single node
 - Does not accommodate group movements
- + Guarantee existence of a time-stationary regime of node mobility state or its non existence.
- + Guarantee convergence of node mobility state to a time-stationary regime, starting a node movement from origin of a trip.

Overview, Cont.

- + Problems on stability of random processes
 - Speed decays to 0 as simulation progresses
 - Conditions for existence of stationary regime or its non existence
 - Conditions for guarantee of convergence to a stationary regime
- + Random trip examples: city driving, circulation models, special purpose models.
- + Perfect Simulation: When condition for stability is satisfied, simulation runs go through a transient period and converge to the stationary regime.
- + Palm Calculus Framework: a set of formulae that relates time averages to event averages. Utilize to derive simple sampling algorithms for the generic random trip model.

Model Definition

- + Domain A is a subset of \mathbb{R}^d for integer $d \geq 1$
- + Phase I is a set of phases on \mathbb{R}^d . A phase describes some state of the mobile, specific to the model (i.e. move/pause at time t)
- + Path P is a set of paths on A . A path is a continuous mapping from $[0, 1]$ to A that has a continuous derivative
 - For $p \in P$, $p(0)$ is the origin of p , $p(1)$ is its destination, $p(u)$ is the point on p attained when $u \in [0, 1]$ of the path is traversed

Model Definition, Cont.

+ Trip is specified by path P_n and a duration S_n :

- $T_n \in \mathbb{R}^+$, $n \in \mathbb{Z}^+$ of transition instants such that $T_0 \leq 0 < T_1 < T_2 < \dots$. At time T_n , a phase $I_n \in I$, a path $P_n \in P$, and a trip duration $S_n \in \mathbb{R}^+$ are drawn according to some specified trip selection rule, specific to the model.
- The next transition instant: $T_{n+1} = T_n + S_n$
- The position of the mobile: $X(t) = P_n[(t-T_n)/S_n]$ for $T_n \leq t \leq T_{n+1}$

+ Trip selection rule is constrained to choose a path P_n such that $P_n(0) = P_{n-1}(1)$

+ Default Initialization Rule: at time $t = 0$, a phase, path, position on the path, and remaining time are drawn according to some specified initialization rule.

Conditions on Phase and Path

(1) $Y \equiv (Y_n)$, $n = [0, +\infty)$ with $Y_n := (I_n, P_n)$ defined as a couple of phase and path is a Markov chain on $I \times P$

(2) The chain Y is Harris recurrent: Ensures that chain Y has unique stationary measure π^0 :

$$\pi^0(A) = \int_{I \times P} P(y, A) \pi^0(dy)$$

(3) The chain Y is positive Harris recurrent: invariant measure π^0 is such that it can be normalized to a probability distribution

Conditions on Trip Duration

- (1) The distribution of a trip duration S_n , given the phase I_n and path P_n is independent of any other past and n
- (2) Each trip takes a strictly positive time
- (3) The Markov renewal process is non arithmetic

Random Trip Examples

+ Random Waypoint with pauses:

- A is convex (rectangle or a disk)
- Paths are straight line segments: $p(u) = (1-u)m_0 + um_1$ for the segment with endpoints m_0 and m_1
- Pauses are special cases of paths when endpoints are equal $p(u) = m_0$
- 2 phases $I = \{\text{pause, move}\}$
- At a transition instant, the trip selection rule alternates the phase from pause to move or vice versa.
 - If the new phase is pause, trip duration S_n is drawn from distribution $F_{0\text{pause}}(s)$.
 - If the new phase is move, the trip selection rules pick a point M_{n+1} at random uniformly in A, and a numerical speed V_n according to the density $F_{0v}(v)$.
- The default initialization rule starts the model at the beginning of a pause, at a location uniformly chosen in A.

+ If M is a random trip model, then M', a model of M with added pauses, is also a random trip model.

Random Trip Examples, Cont.

+ Random Waypoint on General Connected Domain: Variant of the classical random waypoint.

- A is assumed to be a connected domain over which a uniform distribution is well defined (instead of a convex).
- Examples: Swiss Flag, City Section where the domain is the union of segments defined by the edges of space graph.

+ Random Waypoint on Sphere: is a random waypoint on connected, non convex domain.

- Stationary location is uniform.

Random Trip Examples, Cont.

+ Restricted Random Waypoint

- Trip endpoints are selected on a finite set of subdomain $A_i \in R_d$, $i \in L$. A is a convex closure of the subdomains A_i .
 - Let node X starts from a point M_n chosen uniformly at random on a subdomain i . X picks the number of trips r to undergo with trip endpoints in the subdomain i from distribution $F(i)$.
 - The next subdomain is drawn from the distribution $Q(i)$.
 - Assume that Q is an irreducible transition matrix and the number of trips within a subdomain has a finite expectation,
- ⇒ Restricted random waypoint is a random trip model.
- Examples
 - Fish in a bowl - Domain defined by the volume of the bowl.
 - Space graph - a special case with A = the space graph and A_i = the set of vertices

Random Trip Examples, Cont.

+ Random Walk on Torus

- Distribution of location and speed at a random instant are the same as at a transition instant.
- Domain A is the rectangle $[0, a_1] \times [0, a_2]$.
- Paths are wrapped segments - the mobile moves from endpoint M_n in the direction and speed given by the speed vector (according to some fixed distribution) until it hits boundary of A at (x_0, a_2) . Then it is wrapped around to $(x_0, 0)$ where it continues the trip. Wrapping does not modify the speed vector.
- After a trip, a pause time is drawn independent of all past from some fixed distribution. If there is no pause, then it is a random walk on the torus.

+ Assume that the distribution of the speed vector chosen by the trip selection rule has a density. Assume that either the distribution of trip durations or distribution of pause times have a density.

⇒ The random walk on torus satisfies the random trip assumption.

Random Trip Examples, Cont.

+ Billiard

- Wrapping function is replaced by billiard function.
- The billiard reflection may alter the speed vector.

+ Assume that the distribution of the speed vector chosen by the trip selection rule has a density and is completely symmetric. Assume that either the distribution of trip durations or distribution of pause times have a density.

⇒ The billiard satisfies the random trip assumption.

Time Stationarity and Convergence

The state of a mobile node at time t is described by the continuous-time Markov process:

$$\Phi(t) := (Y(t), S(t), S^-(t))$$

$S(t)$ is the duration of the trip at time t . $S^-(t)$ is the elapsed time on the trip at t .

There exists a time-stationarity distribution π for $\Phi(t)$ if and only if $\mathbb{IE}^0(S_0)$ is finite.

$$\pi(B) = \frac{\mathbb{IE}^0 \left(\int_0^{T_1} 1_{\Phi(s) \in B} ds \right)}{\mathbb{IE}^0(S_0)}, \quad B \in I \times \mathcal{P} \times \mathbb{R}_+^2$$

$\mathbb{IE}^0(Z)$ is the Palm Expectation - the expectation, conditional to the event that a transition occur at time 0 , when the system has a stationary regime. $\mathbb{IE}^0(S_0) = \text{Average trip duration}$.

Time Stationary Distribution

+ Perfect Simulation: Sample from the time stationary distribution of the process state - Phase $I(t)$, path $P(t)$, trip duration $S(t)$, where on trip $U(t)$. The time stationary distribution of the process state at an arbitrary time t :

1) *Phase and Path: Let $Y(t) = (I(t), P(t))$.*

$$d\mathbb{P}(Y(t) = y) = \frac{\bar{\tau}(y)}{\int_{\mathcal{Y}} \bar{\tau}(x) \pi^0(dx)} \pi^0(dy).$$

2) *Trip duration, given phase and path:*

$$d\mathbb{P}(S(t) = s | Y(t) = y) = \frac{s}{\bar{\tau}(y)} F(y, ds).$$

3) *Fraction of time elapsed on the trip: $U(t)$ is independent of $(I(t), P(t), S(t))$ and is uniform on $[0, 1]$.*

Apply the Perfect Sampling Algorithm

- + Random Waypoint on Sphere
- + Random Walk on Torus
- + Billiards

For further details, please read the paper.

Thank you for your attention!